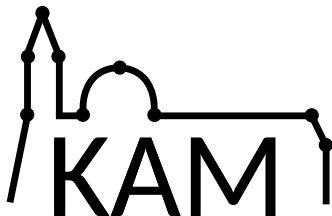


Generalized k -Center: Distinguishing Doubling and Highway Dimension

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June 22, 2022



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OF MATHEMATICS
AND PHYSICS
Charles University

Capacitated k -Center

Input

- ▶ graph $G = (V, E)$ with edge lengths $\ell: E \rightarrow \mathbb{R}^+$,
- ▶ integer k ,
- ▶ capacities $c: V \rightarrow \mathbb{N}$.

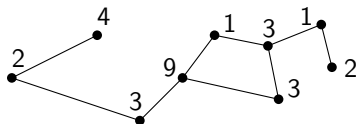


Figure: CKC input with $k = 2$.

Capacitated k -Center: Goal

Find $S \subseteq V$ and an *assignment* $\varphi: (V \setminus S) \rightarrow S$ such that

- ▶ $|S| \leq k$,
- ▶ for every $u \in S$, $|\varphi^{-1}(u)| \leq c(u)$, and
- ▶ $\max_{v \in V \setminus S} \text{dist}(v, \varphi(v))$ is minimal.

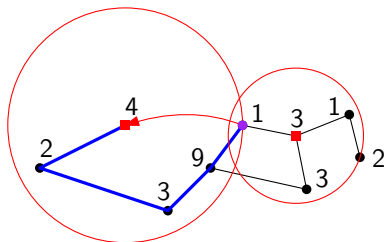


Figure: CkC solution for $k = 2$.

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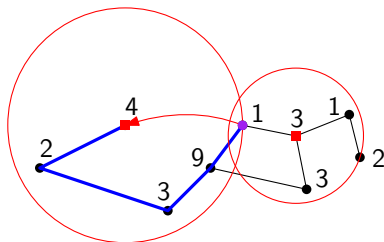


Figure: CKC solution for $k = 2$.

When $c(u) = |V|$ for every $u \in V \Rightarrow k$ -CENTER.

Capacitated k -Center: Solution Prospects

CAPACITATED k -CENTER is NP-hard.

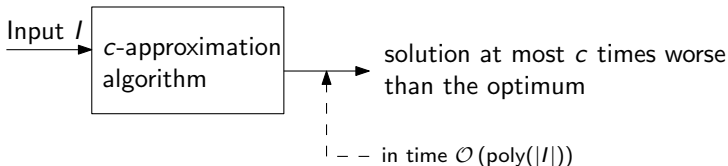
⇒ cannot solve exactly in polynomial time assuming $P \neq NP$.

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c -approximation algorithm

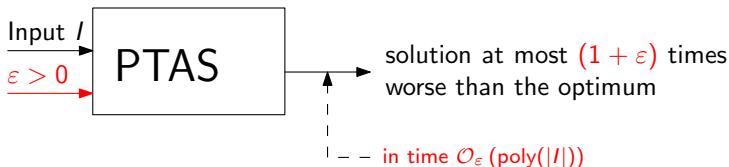


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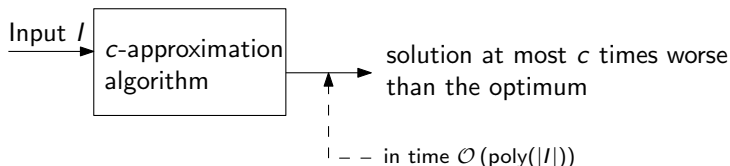
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Polynomial-time approximation scheme



Capacitated k -Center: Solution Prospects

c -approximation algorithm



An, Bhaskara, Chekuri, Gupta, Madan, Svensson. 2015

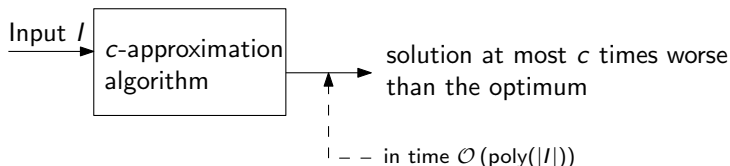
There is a 9-approximation algorithm for CKC .

Cygan, Hajiaghayi, Khuller. 2012

There is no $(3 - \varepsilon)$ -approximation algorithm for CKC unless $P = NP$.

Capacitated k -Center: Solution Prospects

c -approximation algorithm



Cygan, Hajiaghayi, Khuller. 2012

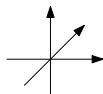
There is no $(3 - \varepsilon)$ -approximation algorithm for CkC unless $P = NP$.

Question

Are there settings where we can overcome this lower bound?

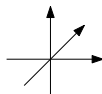
Planar graphs, Euclidean spaces, real world, ...

Special Settings?



	Doubling Dimension (Δ)	
CAPACITATED k -CENTER	<div>generalizes the dimension of ℓ_q spaces</div>	
k -CENTER	$k^k / \varepsilon^{\mathcal{O}(k\Delta)} \cdot \text{poly}(n)$ <small>Feldmann, Marx. 2020</small>	
k -MEDIAN, k -MEANS, FACILITY LOCATION	$2^{(1/\varepsilon)^{\mathcal{O}(\Delta^2)}} \cdot \text{poly}(n)$ <small>Cohen-Addad, Feldmann, Saulpic. 2021</small>	
TSP, STEINER TREE	$\exp\{2^{\mathcal{O}(\Delta)} \cdot (4\Delta \log n / \varepsilon)^\Delta\}$ <small>Talwar. 2004</small>	

Special Settings?

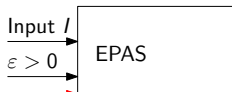


	Doubling Dimension (Δ)	Highway dimension (h)
CAPACITATED k -CENTER		captures properties of transportation networks
k -CENTER	$k^k / \varepsilon^{\mathcal{O}(k\Delta)} \cdot \text{poly}(n)$ Feldmann, Marx. 2020	$f(k, h, \varepsilon) \cdot \text{poly}(n)^\dagger$ Becker, Klein, Saulpic. 2018
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\dagger : f : computable function

Special Settings?

Efficient Parameterized Approximation Scheme



solution at most $(1 + \varepsilon)$ times worse than the optimum

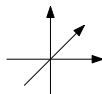
parameter $p \in \mathbb{N} \times \dots \times \mathbb{N}$
of the input

in time $\mathcal{O}(f(p, \varepsilon) \cdot |I|^{\mathcal{O}(1)})$
where f is a computable function

CAPACITY		
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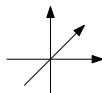
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\S : unless $\text{FPT} = \text{W}[1]$

Doubling Dimension

- ▶ Let $M = (X, \text{dist})$ be a metric space.

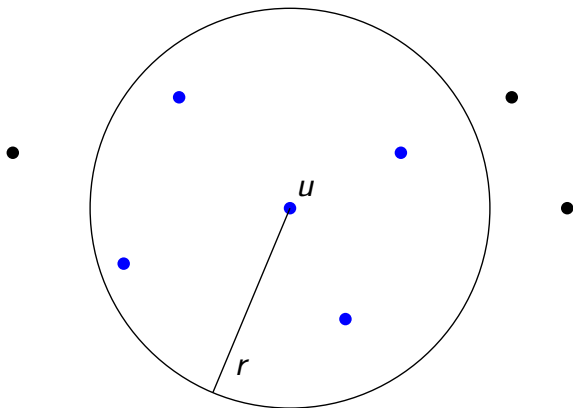
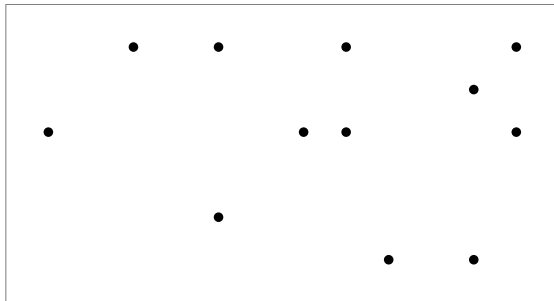


Figure: $B_r(u)$: Ball of radius r .

Doubling Dimension

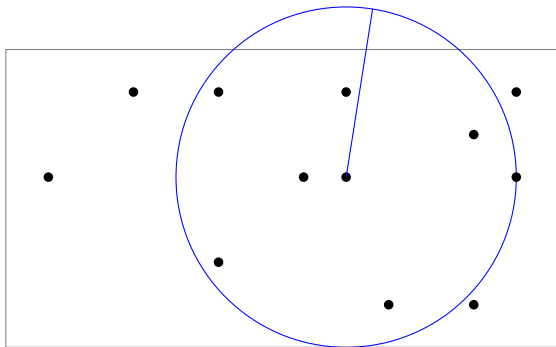
Doubling dimension $\Delta(M)$: smallest $\Delta \in \mathbb{N}$ such that



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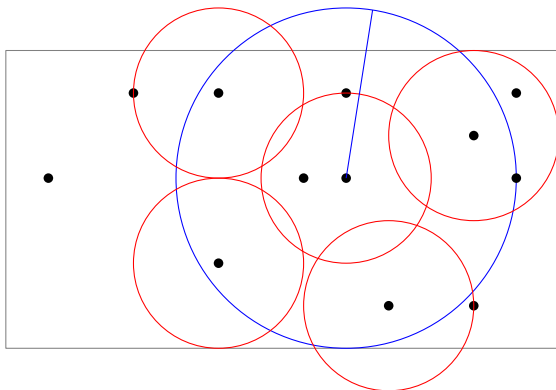
- ▶ the ball $B_r(u)$ for every $u \in X$ and every $r \in \mathbb{R}^+$



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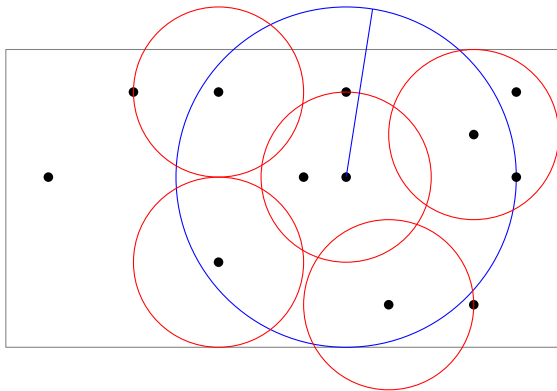
- ▶ the ball $B_r(u)$ for every $u \in X$ and every $r \in \mathbb{R}^+$
- ▶ is contained in $\cup_{v \in V} B_{r/2}(v)$ for some $V \subseteq X$ with $|V| \leq 2^\Delta$.



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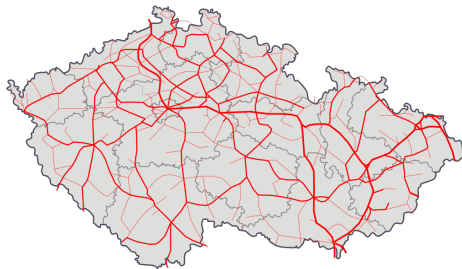
\leadsto d -dimensional ℓ_q metrics have doubling dimension $\mathcal{O}(d)$.

Highway Dimension: Shortest Path Cover

- ▶ Let G be an edge-weighted graph and fix a *scale* $r \in \mathbb{R}^+$.
- ▶ Let \mathcal{P}_r be the set of paths of G such that
 - ▶ they are a shortest path between their endpoints,
 - ▶ their length is more than r and at most $2r$.



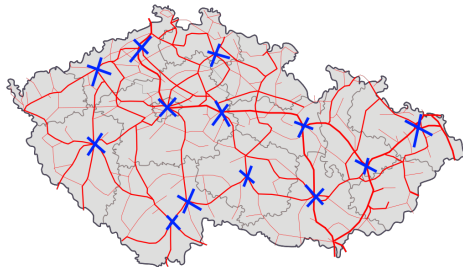
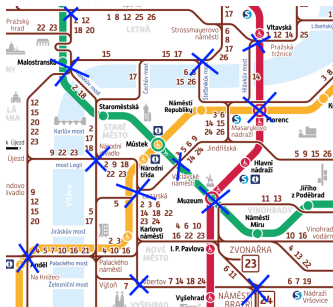
(a) Metro and tram network in Prague city center.



(b) Czech railway network.

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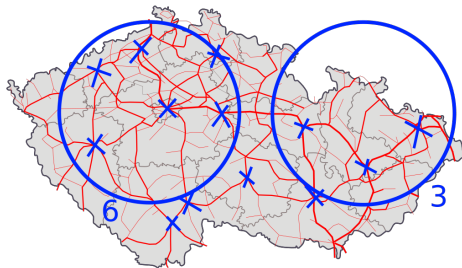
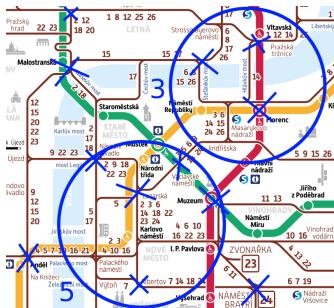
The *shortest path cover* $\text{SPC}_r(G)$ is a hitting set¹ for \mathcal{P}_r .

¹For every $P \in \mathcal{P}_r$ we have $P \cap \text{SPC}_r(G) \neq \emptyset$.

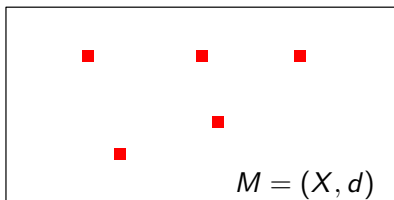
Highway Dimension

highway dimension of an edge-weighted graph G :

- ▶ smallest integer h such that,
- ▶ for any scale $r \in \mathbb{R}^+$,
- ▶ there exists $H := \text{SPC}_r(G)$ so that,
- ▶ $|H \cap B_{2r}(u)| \leq h$ for every $u \in V(G)$.

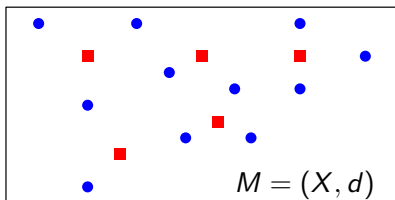


k -CENTER algorithm



■ Optimum solution of cost OPT.

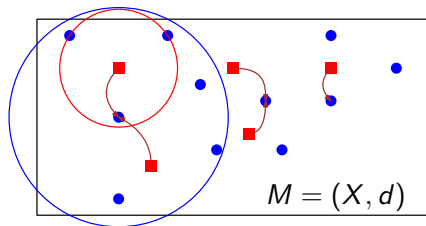
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- **Net:** $Y \subseteq X$ such that
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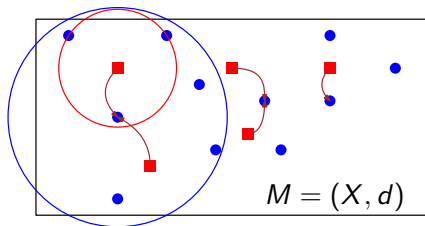
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↪ Replace every optimum center by its nearest net point.

⇒ We get a $(1 + \varepsilon)$ -approximate solution.

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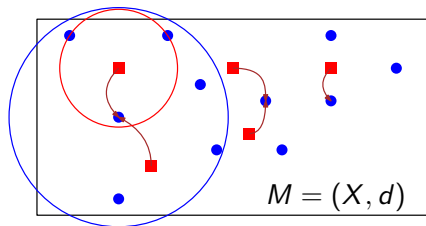
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- It can be shown that $|Y| \leq k(1/\varepsilon)^{O(\Delta)}$.

⇒ Guess the k -tuple near the optimum centers to get an EPAS with parameters k , ε , and Δ .

CkC algorithm obstacles



■ Optimum solution of cost OPT.

CkC obstacles

Capacities?

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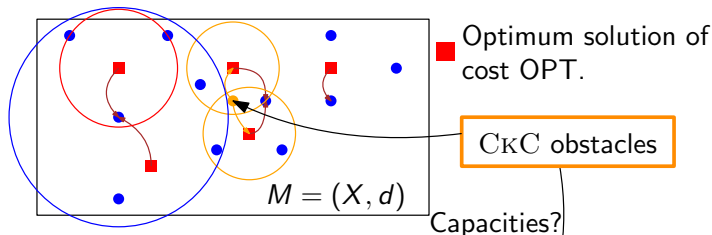
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CkC algorithm obstacles

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CkC obstacles

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Solution recognition?

$M = (X, d)$

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Conclusion

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Thank you for your attention!

Questions, comments, ...?